Omega Commanded

Gain 1

T_ref1 1.0

Scope

Omega

Gain 0.05

Constant 1 2.0

Step

Integrator

Omega

Gain 0.05

T_ref2 1.0

Scope

Omega Commanded

Gain 1

T_m1

PI Controller 1

Gain 0.05

Constant 1 2.0

Step

Integrator

Omega

Gain 0.05

T_m2

PI Controller 2

Omega Commanded

Gain 1

T_m1

PI Controller 1

Gain 0.05

Constant 1 2.0

Step

Integrator

Omega